

**FORECASTING THE TIME-VARYING BETA OF UK COMPANIES
GARCH MODELS VS KALMAN FILTER METHOD**

By

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Abstract

This paper forecast the weekly time-varying beta of 20 UK firms by means of four different GARCH models and the Kalman filter method. The four GARCH models applied are the bivariate GARCH, BEKK GARCH, GARCH-GJR and the GARCH-X model. The paper also compares the forecasting ability of the GARCH models and the Kalman method. Forecast errors based on return forecasts are employed to evaluate out-of-sample forecasting ability of both GARCH models and Kalman method. Measures of forecast errors overwhelmingly support the Kalman filter approach. Among the GARCH models both GJR and GARCH-X models appear to provide a bit more accurate forecasts than the bivariate GARCH model.

Jel Classification: G1, G15

Key Words: Forecasting, Kalman Filter, GARCH, Volatility.

1. Introduction

The standard empirical testing of the Capital Asset Pricing Model (CAPM) assumes that the beta of a risky asset or portfolio is constant (Bos and Newbold, 1984). Fabozzi and Francis (1978) suggest that stock's beta coefficient may move randomly through time rather than remain constant.¹ Fabozzi and Francis (1978) and Bollerslev et al. (1988) provide tests of the CAPM that imply time-varying betas.

As indicated by Brooks et al. (1998) several different econometrical methods have been applied to estimate time-varying betas of different countries and firms. Two of the well methods are the different versions of the GARCH models and the Kalman filter approach. The GARCH models apply the conditional variance information to construct the conditional beta series. The Kalman approach recursively estimates the beta series from an initial set of priors, generating a series of conditional alphas and betas in the market model. Brooks et al. (1998) provide several citations of papers that apply these different methods to estimate the time-varying beta.

Given that the beta is time-varying, empirical forecasting of the beta has become important. Forecasting time-varying beta is important for few reasons. Since the beta (systematic risk) is the only risk that investors should be concern about, prediction of the beta value helps investors to make their investment decisions easier. The value of beta can also be used by market participants to measure the performance of fund managers through Treynor ratio. For corporate financial managers, forecasts of the conditional beta not only benefit them in the capital structure decision but also in investment appraisal.

This paper empirically estimates and attempts to forecast the weekly time-varying beta of twenty UK firms. This paper also empirically investigates the forecasting

¹ According to Bos and Newbold (1984) the variation in the stock's beta may be due to the influence of either microeconomics factors, and/or macroeconomics factors. A detailed discussion of these factors is provided by Rosenberg and Guy (1976a, 1976b).

ability of four different GARCH model; standard bivariate GARCH, bivariate BEKK, bivariate GARCH-GJR and the bivariate GARCH-X. The paper also studies the non-GARCH Kalman filter approach's forecasting ability. A variety of GARCH models have been employed to forecast time-varying betas for different stock markets, (see Bollerslev *et al.* (1988), Engle and Rodrigues (1989), Ng (1991), Bodurtha and Mark (1991), Koutmos *et al.* (1994), Giannopoulos (1995), Braun *et al.* (1995), Gonzalez-Rivera (1996), Brooks *et al.* (1998) and Yun (2002). Similarly the Kalman filter technique has also been used by some studies to forecast the time-varying beta (see Black, *et al.*, 1992 and Well, 1994).

Given the different methods available the empirical question to answer is which econometrical method best forecast the time-varying beta. Although a large literature exists on time-varying beta forecasting models; however no single model is superior. Akgiray (1989) finds the GARCH(1,1) model specification exhibits superior forecasting ability to traditional ARCH, exponentially weighted moving average and historical mean models, using monthly US stock index returns. The apparent superiority of GARCH is also observed in forecasting exchange rate volatility by West and Cho (1995) for one week horizon, although for a longer horizon none of the models exhibits forecast efficiency. On the contrary, Dimson and Marsh (1990) in an examination of the UK equity market conclude that the simple models provide more accurate forecasts than GARCH models.

More recently, empirical studies have been more emphasised on comparison between GARCH models with relatively sophisticated non-linear and non-parametric models. Pagan and Schwert (1990) compare GARCH, EGARCH, Markov switching regime and three non-parametric models for forecasting US stock return volatility. While all non-GARCH models produce very poor predictions; the EGARCH followed

by the GARCH models perform moderately. As a representative applied to exchange rate data, Meade (2002) examines forecasting accuracy of linear AR-GARCH model versus four non-linear methods using five data frequencies and finds that the linear model is not outperformed by the non-linear models. Despite the debate and inconsistency evidence, as Brooks (2002, p. 493) says, it appears that conditional heteroscedasticity models are among the best that are currently available.

Franses and Van Dijk (1996) investigate the performance of the standard GARCH model and non-linear Quadratic GARCH and GARCH-GJR models for forecasting the weekly volatility of various European stock market indices. Their results indicate that non-linear GARCH models can not beat the original model. In particular, the GJR model is not recommended for forecasting. In contrast to their result, Brailsford and Faff (1996) find the evidence favours the GARCH-GJR model for predicting monthly Australian stock volatility, compared with the standard GARCH model. However, Day and Lewis (1992) find limited evidence that, in certain instances, GARCH models provide better forecasts than EGARCH models by out of sample forecast comparison.

Few papers have compared the forecasting ability Kalman filter method with the GARCH models. Brooks et al. (1998) paper investigates three techniques for the estimation of time-varying betas: GARCH; a time-varying beta market model approach suggested by Schwert and Seguin (1990); and Kalman filter. According in-sample and out-of-sample return forecasts based on beta estimates, Kalman filter is superior to others. Faff et al. (2000) finds all three techniques are successful in characterising time-varying beta. Comparison based on forecast errors support that time-varying betas estimated by Kalman filter are more efficient than other models.

2. The (conditional) CAPM and the Time-Varying Beta

One of the assumptions of the capital asset pricing model (CAPM) is that all investors have the same subjective expectations on the means, variances and covariances of returns.² According to Bollerslev et al. (1988) economic agents may have common expectations on the moments of future returns but these are conditional expectations and therefore random variables rather than constant.³ The CAPM that takes conditional expectations into consideration is sometimes known as conditional CAPM. The conditional CAPM provides a convenient way to incorporate the time-varying conditional variances and covariances (Bodurtha and Mark, 1991).⁴ An asset's beta in the conditional CAPM can be expressed as the ratio of the conditional covariance between the forecast error in the asset's return, and the forecast's error of the market return and the conditional variance of the forecast error of the market return.

The following analysis relies heavily on Bodurtha and Mark (1991). Let $R_{i,t}$ be the nominal return on asset i ($i= 1, 2, \dots, n$) and $R_{m,t}$ the nominal return on the market portfolio m . The excess (real) return of asset i and market portfolio over the risk-free asset return is presented by $r_{i,t}$ and $r_{m,t}$ respectively. The conditional CAPM in excess returns may be given as

$$E(r_{i,t}|\Pi_{t-1}) = \beta_{i|t-1} E(r_{m,t}|\Pi_{t-1}) \quad (1)$$

where,

² See Markowitz (1952), Sharpe (1964) and Lintner (1965) for details of the CAPM.

³ According to Klemkosky and Martin (1975) betas will be time-varying if excess returns are characterized by conditional heteroscedasticity.

⁴ Hansen and Richard (1987) have shown that omission of conditioning information, as is done in tests of constant beta versions of the CAPM, can lead to erroneous conclusions regarding the conditional mean variance efficiency of a portfolio.

$$\beta_{i|t-1} = \text{cov}(R_{i,t}, R_{m,t} | I_{t-1}) / \text{var}(R_{m,t} | I_{t-1}) = \text{cov}(r_{i,t}, r_{m,t} | I_{t-1}) / \text{var}(r_{m,t} | I_{t-1}) \quad (2)$$

and $E(I_{t-1})$ is the mathematical expectation conditional on the information set available to the economic agents last period (t-1), I_{t-1} . Expectations are rational based on Muth (1961)'s definition of rational expectation where the mathematical expected values are interpreted as the agent's subjective expectations. According to Bodurtha and Mark (1991) asset i 's risk premium varies over time due to three time-varying factors: the market's conditional variance, the conditional covariance between asset's return, and the market's return and/or the market's risk premium. If the covariance between asset i and the market portfolio m is not constant then the equilibrium returns $R_{i,t}$ will not be constant. If the variance and the covariance are stationary and predictable then the equilibrium returns will be predictable.

3. Bivariate GARCH, BEKK GARCH, GARCH-X and BEKK GARCH-X Models

3.1 Bivariate GARCH

As shown by Baillie and Myers (1991) and Bollerslev et al. (1992), weak dependence of successive asset price changes may be modelled by means of the GARCH model. The multivariate GARCH model uses information from more than one market's history. According to Engle and Kroner (1995), multivariate GARCH models are useful in multivariate finance and economic models, which require the modelling of both variance and covariance. Multivariate GARCH models allow the variance and covariance to depend on the information set in a vector ARMA manner (Engle and Kroner, 1995). This, in turn, leads to the unbiased and more precise estimate of the parameters (Wahab, 1995).

The following bivariate GARCH(p,q) model may be used to represent the log difference of the company stock index and the market stock index:

$$y_t = \mu + \varepsilon_t \quad (3)$$

$$\varepsilon_t/\Omega_{t-1} \sim N(0, H_t) \quad (4)$$

$$\text{vech}(H_t) = C + \sum_{j=1}^p A_j \text{vech}(\varepsilon_{t-j})^2 + \sum_{j=1}^q B_j \text{vech}(H_{t-j}) \quad (5)$$

where $y_t = (r_t^c, r_t^f)$ is a (2x1) vector containing the log difference of the firm (r_t^c) stock index and market (r_t^f) index; H_t is a (2x2) conditional covariance matrix; C is a (3x1) parameter vector (constant); A_j and B_j are (3x3) parameter matrices; and vech is the column stacking operator that stacks the lower triangular portion of a symmetric matrix. We apply the GARCH model with diagonal restriction.

Given the bivariate GARCH model of the log difference of the firm and the market indices presented above, the time-varying beta can be expressed as:

$$\beta_t = \hat{H}_{12,t} / \hat{H}_{22,t} \quad (6)$$

Where $\hat{H}_{12,t}$ is the estimated conditional variance between the log difference of the firm index and market index, and $\hat{H}_{22,t}$ is the estimated conditional variance of the log difference of the market index from the bivariate GARCH model. Given that conditional covariance is time-dependent, the beta will be time-dependent.

3.2 Bivariate BEKK GARCH

Lately, a more stable GARCH presentation has been put forward. This presentation is termed by Engle and Kroner (1995) the BEKK model; the conditional covariance matrix is parameterized as

$$\text{vech}(H_t) = C'C + \sum_{k=1}^K \sum_{i=1}^q A'_{Ki} \varepsilon_{t-i} \varepsilon'_{t-i} A_{ki} + \sum_{k=1}^K \sum_{j=1}^p B'_{Kj} H_{t-j} B_{kj} \quad (7)$$

Equations 3 and 4 also apply to the BEKK model and are defined as before. In equation 7 A_{ki} , $i = 1, \dots, q$, $k = 1, \dots, K$, and B_{kj} $j = 1, \dots, p$, $k = 1, \dots, K$ are all $N \times N$ matrices. This formulation has the advantage over the general specification of the multivariate GARCH that conditional variance (H_t) is guaranteed to be positive for all t (Bollerslev et al., 1994). The BEKK GARCH model is sufficiently general that it includes all positive definite diagonal representation, and nearly all positive definite vector representation. The following presents the BEKK bivariate GARCH(1,1), with $K=1$.

$$H_t = C'C + A' \varepsilon_{t-1} \varepsilon'_{t-1} A + B' H_{t-1} B \quad (7a)$$

where C is a 2×2 lower triangular matrix with intercept parameters, and A and B are 2×2 square matrices of parameters. The bivariate BEKK GARCH(1,1) parameterization requires estimation of only 11 parameters in the conditional variance-covariance structure, and guarantees H_t positive definite. Importantly, the BEKK model implies that only the magnitude of past returns innovations is important in determining current conditional variances and co-variances. The time-varying beta

is based on the BEKK GARCH model is also expressed as equation 6. Once again we apply the BEKK GARCH model with diagonal restriction.

3.3 GARCH-GJR

Along with the leptokurtic distribution of stock returns data, negative correlation between current returns and future volatility have been shown by empirical research (Black, 1976 and Christie, 1982). This negative effect of current returns on future variance is sometimes called the leverage effect (Bollerslev et al. 1992). The leverage effect is due to the reduction in the equity value which would raise the debt-to-equity ratio, hence raising the riskiness of the firm as a result of an increase in future volatility. Thus, according to the leverage effect stock returns, volatility tends to be higher after negative shocks than after positive shocks of a similar size. Glosten et al. (1993) provide an alternative explanation for the negative effect; if most of the fluctuations in stock prices are caused by fluctuations in expected future cash flows, and the riskiness of future cash flows does not change proportionally when investors revise their expectations, the unanticipated changes in stock prices and returns will be negatively related to unanticipated changes in future volatility.

In the linear (symmetric) GARCH model the conditional variance is only linked to past conditional variances and squared innovations (ε_{t-1}), and hence the sign of return plays no role in affecting volatilities (Bollerslev et al. 1992). Glosten et al. (1993) provide a modification to the GARCH model that allows positive and negative innovations to returns to have different impact on conditional variance.⁵ This modification involves adding a dummy variable (I_{t-1}) on the innovations in the

⁵ There is more than one GARCH model available that is able to capture the asymmetric effect in volatility. Pagan and Schwert (1990), Engle and Ng (1993), Hentschel (1995) and Fornari and Mele (1996) provide excellent analyses and comparisons of symmetric and asymmetric GARCH models. According to Engle and Ng (1993) the Glosten et al. (1993) model is the best at parsimoniously capturing this asymmetric effect.

conditional variance equation. The dummy (I_{t-1}) takes the value one when innovations (ε_{t-1}) to returns are negative, and zero otherwise. If the coefficient of the dummy is positive and significant, this indicates that negative innovations have a larger effect on returns than positive innovations. A significant effect of the dummy implies nonlinear dependencies in the returns volatility.

Gloster et al. (1993) suggest that the asymmetry effect can also be captured simply by incorporating a dummy variable in the original GARCH.

$$\sigma_t^2 = \alpha_0 + \alpha u_{t-1}^2 + \gamma u_{t-1}^2 I_{t-1} + \beta \sigma_{t-1}^2 \quad (8)$$

Where $I_{t-1} = 1$ if $u_{t-1} > 0$; otherwise $I_{t-1} = 0$. Thus, the ARCH coefficient in a GARCH-GJR model switches between $\alpha + \gamma$ and α , depending on whether the lagged error term is positive or negative. Similarly, this version of GARCH model can be applied to two variables to capture the conditional variance and covariance. The time-varying beta is based on the GARCH-GJR model is also expressed as equation 6.

3.3 Bivariate GARCH-X

Lee (1994) provides an extension of the standard GARCH model linked to an error-correction model of cointegrated series on the second moment of the bivariate distributions of the variables. This model is known as the GARCH-X model. According to Lee (1994), if short-run deviations affect the conditional mean, they may also affect conditional variance, and a significant positive effect may imply that the further the series deviate from each other in the short run, the harder they are to predict. If the error correction term (short-run deviations) from the cointegrated relationship between company index and market index affects the conditional variance (and conditional covariance), then conditional heteroscedasticity may be

modelled with a function of the lagged error correction term. If shocks to the system that propagate on the first and the second moments change the volatility, then it is reasonable to study the behaviour of conditional variance as a function of short-run deviations (Lee, 1994). Given that short-run deviations from the long-run relationship between the company and market stock indices may affect the conditional variance and conditional covariance, then they will also influence the time-varying beta, as defined in equation 6.

The following bivariate GARCH(p,q)-X model may be used to represent the log difference of the company and the market indices:

$$\text{vech}(H_t) = C + \sum_{j=1}^p A_j \text{vech}(\varepsilon_{t-j})^2 + \sum_{j=1}^q B_j \text{vech}(H_{t-j}) + \sum_{j=1}^k D_j \text{vech}(z_{t-1})^2 \quad (9)$$

Once again, equations 3 and 4 (defined as before) also apply to the GARCH-X model. The squared error term (z_{t-1}) in the conditional variance and covariance equation (equation 9) measures the influences of the short-run deviations on conditional variance and covariance. The cointegration test between the log of the company stock index and the market index is conducted by means of the Engle-Granger (1987) test.⁶

As advocated by Lee (1994, p. 337), the square of the error-correction term (z) lagged once should be applied in the GARCH(1,1)-X model. The parameters D_{11} and

⁶ The following cointegration relationship is investigated by means of the Engle and Granger (1987) method:

$$S_t = \eta + \gamma F_t + z_t$$

Where S_t and F_t are log of firm stock index and market price index, respectively. The residuals z_t are tested for unit root(s) to check for cointegration between S_t and F_t . The error correction term, which represents the short-run deviations from the long-run cointegrated relationship, has important predictive powers for the conditional mean of the cointegrated series (Engle and Yoo, 1987). Cointegration is found between the log of company index and market index for five firms. These results are available on request.

D_{33} indicate the effects of the short-run deviations between the company stock index and the market stock index from a long-run cointegrated relationship on the conditional variance of the residuals of the log difference of the company and market indices, respectively. The parameter D_{22} shows the effect of the short-run deviations on the conditional covariance between the two variables. Significant parameters indicate that these terms have potential predictive power in modelling the conditional variance-covariance matrix of the returns. Therefore, last period's equilibrium error has significant impact on the adjustment process of the subsequent returns. If D_{33} and D_{22} are significant, then H_{12} (conditional covariance) and H_{22} (conditional variance of futures returns) are going to differ from the standard GARCH model H_{12} and H_{22} . For example, if D_{22} and D_{33} are positive, an increase in short-run deviations will increase H_{12} and H_{22} . In such a case, the GARCH-X time-varying beta will be different from the standard GARCH time-varying beta.

The methodology used to obtain the optimal forecast of the conditional variance of a time series from a GARCH model is the same as that used to obtain the optimal forecast of the conditional mean (Harris and Sollis 2003, p. 246)⁷. The basic univariate GARCH(p, q) is utilised to illustrate the forecast function for the conditional variance of the GARCH process due to its simplicity.

$$\sigma_t^2 = \alpha_0 + \sum_{i=1}^q \alpha_i u_{t-i}^2 + \sum_{j=1}^p \beta_j \sigma_{t-j}^2 \quad (10)$$

Providing that all parameters are known and the sample size is T , taking conditional expectation the forecast function for the optimal h -step-ahead forecast of the conditional variance can be written:

⁷ Harris and Sollis (2003, p. 247) discuss the methodology in details.

$$E(\sigma_{T+h}^2 | \Omega_T) = \alpha_0 + \sum_{i=1}^q \alpha_i (u_{T+h-i}^2 | \Omega_T) + \sum_{j=1}^p \beta_j (\sigma_{T+h-i}^2 | \Omega_T) \quad (11)$$

Where Ω_T is the relevant information set. For $i \leq 0$, $E(u_{T+i}^2 | \Omega_T) = u_{T+i}^2$ and $E(\sigma_{T+i}^2 | \Omega_T) = \sigma_{T+i}^2$; for $i > 0$, $E(u_{T+i}^2 | \Omega_T) = E(\sigma_{T+i}^2 | \Omega_T)$; and for $i > 1$, $E(\sigma_{T+i}^2 | \Omega_T)$ is obtained recursively. Consequently, the one-step-ahead forecast of the conditional variance is given by:

$$E(\sigma_{T+1}^2 | \Omega_T) = \alpha_0 + \alpha_1 u_T^2 + \beta_1 \sigma_T^2 \quad (12)$$

Although many GARCH specifications forecast the conditional variance in a similar way, the forecast function for some extensions of GARCH will be more difficult to derive. For instance, extra forecasts of the dummy variable I are necessary in the GARCH-GJR model. However, following the same framework, it is straightforward to generate forecasts of the conditional variance and covariance using bivariate GARCH models, and thus the conditional beta.

4. Kalman Filter Method

In the engineering literature of the 1960s, an important notion called ‘state space’ was developed by control engineers to describe system that vary through time. The general form of a state space model defines an observation (or measurement) equation and a transition (or state) equation, which together express the structure and dynamics of a system.

In a state space model, observation at time t is a linear combination of a set of variables, known as state variables, which compose the state vector at time t . Denote

the number of state variables by m and the $(m \times 1)$ vector by θ_t , the observation equation can be written as

$$y_t = z_t' \theta_t + u_t \quad (13)$$

Where z_t is assumed to be a known the $(m \times 1)$ vector, and u_t is the observation error. The disturbance u_t is generally assumed to follow the normal distribution with zero mean, $u_t \sim N(0, \sigma_u^2)$. The set of state variables may be defined as the minimum set of information from present and past data such that the future value of time series is completely determined by the present values of the state variables. This important property of the state vector is called the Markov property, which implies that the latest value of variables is sufficient to make predictions.

A state space model can be used to incorporate unobserved variables into, and estimate them along with, the observable model to impose a time-varying structure of the CAPM beta (Faff *et al.*, 2000). Additionally, the structure of the time-varying beta can be explicitly modelled within the Kalman filter framework to follow any stochastic process. The Kalman filter recursively forecasts conditional betas from an initial set of priors, generating a series of conditional intercept and beta coefficients for the CAPM.

The Kalman filter method estimates the conditional beta using the following regression,

$$R_{it} = \alpha_t + \beta_{it} R_{Mt} + \varepsilon_t \quad (14)$$

Where R_{it} and R_{Mt} is the excess return on the individual share and the market portfolio at time t , and ε_t is the disturbance term. The equation (14) represents the observation equation of the state space model, which is similar to the CAPM model. However, the form of the transition equation depends on the form of stochastic process that betas are assumed to follow. In other words, the transition equation can be flexible, such as using AR(1) or random walk process. According to Faff *et al.* (2000), the random walk gives the best characterisation of the time-varying beta, while AR(1) and random coefficient forms of transition equation encounter the difficulty of convergence for some return series. Failure of convergence is indicative of a misspecification in the transition equation. Therefore, this paper considers the form of random walk; and thus the corresponding transition equation is

$$\beta_{it} = \beta_{it-1} + \eta_t \quad (15)$$

Equation (14) and (15) constitute a state space model. In addition, prior conditionals are necessary for using the Kalman filter to forecast the future value, which can be expressed by

$$\beta_0 \sim N(\beta_0, P_0) \quad (16)$$

The first two observations can be used to establish the prior condition. Based on the prior condition, the Kalman filter can recursively estimate the entire series of conditional beta.

5. Data and Forecasting time-varying beta series

The data applied is weekly ranging from January 1989 to December 2003. Twenty UK firms are selected based on size (market capitalization), industry and the product/service provided by the firm. Table 1 provides the details on the firms under study. The stock returns are created by taking the first difference of the log of the stock indices. The excess stock returns are created by subtracting the return on a risk-free asset from the stock returns. The risk-free asset applied is the UK Treasury Bill Discount 3 Month. The proxy for market return is the return on index of FTSE all share.

To avoid the sample effect and overlapping issue, three forecast horizons are considered, including two one-year forecast horizons (2001 and 2003) and a two-year forecast horizon (2002 to 2003). All models are estimated for the periods 1989-2000, 1989-2001 and 1989-2002, and the estimated parameters are applied for forecasting over the forecast samples 2001, 2002-2003 and 2003.

The methodology of forecasting time-varying betas will be carried out in several steps. In the first step, the actual beta series will be constructed by GARCH models and the Kalman filter approach from 1989 to 2003. In the second step, the forecasting models will be used to forecast time-varying betas and be compared in terms of forecasting accuracy. The lack of *ex ante* beta values makes it impossible to evaluate the predictive ability of models according to the real future benchmarks. Consequently, *ex post* data must be used as remediation. For instance, sequences of beta will be 'predicted' for the year 2003 based on parameter values derived from 1989 to 2002. Forecasted betas then will be compared to real beta values in 2003. In the third and last step, the empirical results of performance of various models will be produced on the basis of hypothesis tests whether the estimate is significantly

different from the real value, which will provide evidences for comparative analysis of merits of different forecasting models.

It is important to point out that the lack of benchmark is an inevitable weak point of studies on time-varying beta forecasts, since the beta value is unobservable in the real world. Although the point estimation of beta generated by the market model is a moderate proxy for the actual beta value, it is not an appropriate scale to measure a beta series forecasted with time variation. As a result, evaluation of forecast accuracy based on comparing conditional betas estimated and forecasted by the same approach cannot provide compelling evidence of the worth of the approach. To assess predictive performance, a logical extension is to examine returns out-of-sample. Recall the conditional CAPM equation

$$E(r_{i,t}|I_{t-1}) = \beta_{i,t-1} E(r_{m,t}|I_{t-1}) \quad (17)$$

With the out-of-sample forecasts of conditional betas, the out-of-sample forecasts of returns can be easily calculated by equation (17), in which the market return and the risk free rate of return are actual returns observed. The relative accuracy of conditional beta forecasts then can be assessed by comparing the return forecasts with the actual returns. In this way, the issue of missing benchmark can be settled.⁸

6. Measures of Forecast Accuracy

A group of measures derived from the forecast error are designed to evaluate *ex post* forecasts. This family of measures of forecast accuracy includes mean squared error (MSE), root mean squared error (RMSE), mean error (ME), mean absolute error (MAE), mean squared percent error (MSPE) and root mean squared error (RMSPE)

⁸ Brooks et al. (1998) provide a comparison in the context of the market model.

and some other standard measures. Among them, the most common overall accuracy measures are MSE and MSPE (Diebold 2004, p. 298):

$$MSE = \frac{1}{n} \sum_{t=1}^n e_t^2 \quad (18)$$

$$MSPE = \frac{1}{n} \sum_{t=1}^n p_t^2 \quad (19)$$

Where e is the forecast error defined as the difference between the actual value and the forecasted value and p is the percentage form of the forecast error. Very often, the square roots of these measures are used to preserve units, as it is in the same units as the measured variable. In this way, the root mean square error is sometimes a better descriptive statistic. However, since the beta is a value without unit, MSE can be competent measures in this research.

The lower the forecast error measure, the better the forecasting performance. However, it does not necessarily mean that a lower MSE completely testifies superior forecasting ability, since the difference between the MSEs may be not significantly different from zero. Therefore, it is important check whether any reductions in MSEs are statistically significant, rather than just compare the MSE of different forecasting models (Harris and Sollis 2003, p. 250).

Diebold and Mariano (1995) develop a test of equal forecast accuracy to test for whether two sets of forecast errors, say e_{1t} and e_{2t} , have equal mean value. Using MSE as the measure, the null hypothesis of equal forecast accuracy can be represented as $E[d_t] = 0$, where $d_t = e_{1t}^2 - e_{2t}^2$. Supposed n , h -step-ahead forecasts have

been generated, Diebold and Mariano (1995) suggest the mean of the difference

between MSEs $\bar{d} = \frac{1}{n} \sum_{t=1}^n d_t$ has an approximate asymptotic variance of

$$\text{Var}(\bar{d}) \approx \frac{1}{n} \left[\gamma_0 + 2 \sum_{k=1}^{h-1} \gamma_k \right] \quad (20)$$

Where γ_k is the k th autocovariance of d_t , which can be estimated as:

$$\hat{\gamma}_k = \frac{1}{n} \sum_{t=k+1}^n (d_t - \bar{d})(d_{t-k} - \bar{d}) \quad (21)$$

Therefore, the corresponding statistic for testing the equal forecast accuracy hypothesis is $S = \bar{d} / \sqrt{\text{Var}(\bar{d})}$, which has an asymptotic standard normal distribution.

According to Diebold and Mariano (1995), results of Monte Carlo simulation experiments show that the performance of this statistic is good, even for small samples and when forecast errors are non-normally distributed. However, this test is found to be over-sized for small numbers of forecast observations and forecasts of two-steps ahead or greater.

Harvey *et al.* (1997) further develop the test for equal forecast accuracy by modifying Diebold and Mariano's (1995) approach. Since the estimator used by Diebold and Mariano (1995) is consistent but biased; Harvey *et al.* (1997) improve the finite sample performance of Diebold and Mariano (1995) test using an approximately unbiased estimator of the variance of \bar{d} . The modified test statistic is given by

$$S^* = \left[\frac{n+1-2h+n^{-1}h(h-1)}{n} \right]^{1/2} S \quad (22)$$

Through Monte Carlo simulation experiments, this modified statistics is found to perform much better than the original Diebold and Mariano statistic at all forecast horizon and when the forecast errors are autocorrelated or have non-normal distribution. In this paper we apply both the Diebold and Mariano test and the modified Diebold and Mariano test but only the results from the second test are presented. Results from the standard Diebold and Mariano tests are available on request.

7. GARCH and Kalman Method Results

The GARCH model results obtained for all periods are quite standard for equity market data. Given their bulkiness, these results are not provided in order to save space but are available on request. The GARCH-X model is only estimated for five companies; BT Group, Legal and General, British Vita, Alvis and Care UK. This is because cointegration between the log of the company stock index and the log of the market stock index is only found for these five companies. The cointegration results are available on request. For the GARCH models except the BEKK the BHHH algorithm is used as the optimisation method to estimate the time-varying beta series. For the BEKK GARCH the BFGS algorithm is applied.

The Kalman filter approach is the non-GARCH models applied in competition with GARCH for predicting the conditional beta. Once again, BHHH algorithm is used as the optimisation method to estimate the twenty time-varying beta series. Although the random walk gives the best characterisation of the conditional beta with highest convergence rates and shortest time to converge (see Faff *et al.*, 2000 for

example), four firms (Singet Group, Caldwell Invs, Alvis and Tottenham Hotspur) fail to converge to a unique solution when the random walk is chosen as the form of transition equation. This is indicative of a misspecification in the transition equation. In order to obtain the unique solution, AR(1), constant mean (plus noise), random walk with drift are considered as alternative forms of transition equation for these companies. However, no convergence can be achieved, implying that alternative transition equations are no better than the random walk. The Kalman filter results are also available on request.

The basic statistics indicate that the time-varying conditional betas estimated by means of the different GARCH models have positive and significant mean values. Most beta series show significant excess kurtosis. Hence, most conditional betas are leptokurtic. All beta series are rejected for normality with the Jarque-Bera statistics, usually at the 1% level. Compared to the results of GARCH models, betas generated by the Kalman Filter approach show some different features. First, not all conditional betas can be calculated by means of Kalman Filter approach. Second, conditional betas have a wider range than those constructed by GARCH models. Third, skewness, kurtosis and Jarque-Bera statistics are more diversified. There are very few cases of symmetric distribution, mesokurtic and a single case of normal distribution. These basic statistics of the estimated beta series is available on request.⁹

8. Forecasting Conditional Betas and Forecast Accuracy

As stated earlier to avoid the sample effect and overlapping issue, three forecast horizons are considered, including two one-year forecast horizons (2001 and 2003)

⁹ The augmented Dickey-Fuller test is applied to check for the stochastic structure of the beta series. All GARCH estimated beta series are found to have zero unit roots. Some of the beta estimated by means of the Kalman filter approach may contain one unit root. Therefore, conditional betas estimated by Kalman filter show a different feature of dynamic structure from the ones generated by GARCH models. These results are also available on request.

and a two-year forecast horizon (2002 to 2003). In this way, beta forecasts series can be compared to actual betas in the forecast horizon to assess forecast accuracy of each model¹⁰.

As indicated earlier in order to evaluate the level of forecast errors between conditional beta forecasts and actual values, mean absolute errors (MAE), mean square errors (MSE), mean absolute percentage errors (MAPE) and Theil U statistics are calculated for each forecast. We only provide a summary of the results here but the actual results are available on request.

The GJR GARCH model produce the most accurate beta forecasts in the out-of-sample period 2001, followed by bivariate GARCH, GARCH-X and Kalman filter models. BEKK has the poorest forecasting performance. Franses and Van Dijk (1996) and Brailsford and Faff (1996) also find evidence favouring the GJR model. For 2003 overall, bivariate GARCH is the model with most accurate beta forecasts in 2003, followed by Kalman filter and GJR GARCH. GARCH-X produces moderate conditional beta forecasts. BEKK is inferior to others in terms forecasting ability. The longer out-of-sample forecast in 2002-2003 helps to evaluate the forecasting performance of alternative models in a longer forecast horizon. Accordingly, GJR GARCH is argued to be the most accurate model in the two-year out-of-sample forecasts. Bivariate GARCH also performs considerably accurate prediction. Kalman filter is not as precise as in the shorter forecast period (2003).

Given relative superiority of alternative models in different out-of-sample periods, we can generally conclude that bivariate GARCH is the most accurate forecasting model in one-year forecast sample. However, when the market is extremely volatile, GJR GARCH is the most successful forecasting technique, allowing for the

¹⁰ Due to difficulty of converge, Kalman filter only produces fourteen forecasts in the holdout sample 2001, fifteen forecasts in 2003 and sixteen forecasts in 2002-2003.

asymmetric effect. Kalman filter fits to the shorter forecast sample without significant volatility, but is less competent to forecast betas with extremely time variant features. This confirms that the Kalman filter method is somewhat inferior to GARCH models in capturing time-variation of beta series. For the longer forecast horizon, GJR GARCH performs better than its competitors. Bivariate GARCH is still successful for the longer forecast sample under analysis. Performance of Kalman filter approach seems to be degenerative when the out-of-sample period becomes longer. GARCH-X generates consistently accurate beta forecasts, regardless of forecast horizons and market situations, which can be arguably due to the error correction terms incorporated in the model. BEKK is the model with most inaccurate forecast results over different holdout samples.

9. Forecast Errors Based on Return Forecasts

To evaluate return forecasts, different measures of forecast errors are employed. Since the return series and forecasts are fairly small in size and can take on opposite signs, MAPE and Theil U statistics are not reliable criterion in this case. In addition, mean errors (ME) are employed to assess whether the models over or under forecast return series. Thus, MAE, MSE and ME are the criteria to evaluate return forecasting performance.

Errors of out-of-sample return forecasts in 2001 are presented in Tables 2, 3 and 4. In Table 2, Kalman filter is favoured with eleven lowest MAE values in all fourteen applicable instances. The simple GARCH model dominates when Kalman filter fails to converge, with the smallest MAE for six firms. BEKK is found to be accurate in forecasting returns with two firms, which is contrasting to evaluation results based on beta forecasts. GJR seems to be relatively less successful to predict returns, with only one smallest MAE. GARCH-X produces moderate return forecasts and wins no

competitions. Examining Table 3, the similar result is evident that Kalman filter approach performs better than the other models. It has the lowest MSE for thirteen shares. Bivariate GARCH dominates in five cases; while BEKK outperforms the others in the rest two competitions. All forecasting models tends to over predict the return values in 2001, as indicated by Table 4 in which most ME are positive. The general over-prediction is reasonable, given the fact the financial market was significantly deteriorated by the tragic events of September 11.

Tables 5, 6 and 7 show the error of out-of-sample return forecast for 2003. Table 5 reports MAE of return forecasts in the forecast sample period 2003. Again, Kalman filter is found to be the most successful forecasting approaches. GJR is the second competent model with the lowest MAE for six shares. Bivariate GARCH and BEKK have similar level of forecast errors, each dominating in two cases. In Table 6, Kalman filter is confirmed to be the best in forecasting share returns when the popular quadratic loss function is used. GJR produces relatively more accurate return forecasts for five firms. BEKK and the simple GARCH have similar performance, with three and one lowest MSE respectively. According to ME reported in Table 7, no significant tendency of too high or too low forecasts is found.

Forecast errors for the two-year out-of-sample 2002-2003 are reported in Tables 8, 9 and 10. MAE results in Table 8 indicates that Kalman filter dominate the other forecasting models by having eleven smallest MAEs. Bivariate GARCH has three lowest MAEs; and the other models seem to have similar predictive performance, each having the lowest MAE for two firms. Table 9 presents MSE of return forecasts in the two-year holdout sample. Once again, Kalman filter approach is favoured by MSE with the lowest values for thirteen shares. GARCH type models show comparable forecasting accuracy, each having one or two smallest MSEs. In Table 10,

positive and negative values of ME are mixed, implying all models do not tend to over or under forecast returns.

In summary, evaluation of forecast accuracy based on return forecasts provides different information on relative superiority of alternative models. Kalman filter approach is the best model, when forecasted returns are compared to real values. It dominates GARCH models in most cases for different forecast samples. Similar conclusion is also reached by Brooks et al. (1998) and Faff et al. (2000). All GARCH based models produce comparably accurate return forecasts. Interestingly, BEKK is acceptable in terms of return forecasts, although it performs poorly when evaluated in terms of beta forecasts.

Figure 1 shows the return forecasted by the different methods and the actual return over the longer period (2002-2003) for two firms. All estimates seem to move together with the actual return but the Kalman filter forecast shows the closest correlation. Figures of other firms are available on request.

10. Modified Diebold and Mariano Tests

As stated earlier Harvey *et al.* (1997) propose a modified version that corrects for the tendency of the Diebold-Mariano statistic to be biased in small samples. Out-of-sample forecasts on the weekly basis are fairly finite with 52 observations in the one-year forecast horizon. In this case, the modified Diebold-Mariano statistics are more reliable and apposite for ranking the various forecasting models candidates than the original Diebold-Mariano statistics. Two criteria, including MSE and MAE derived from return forecasts, are employed to implement the modified Diebold-Mariano tests. Each time, the tests are conducted to detect superiority between two forecasting models; and thus there are ten groups of test for five models. For each group, there are

a number of modified Diebold-Mariano tests for both MSE and MAE from return forecasts, between all applicable firms and through three forecast samples.

Each modified Diebold-Mariano test generates two statistics, S_1 and S_2 , based on two hypotheses:

1. H_0^1 : there is no statistical difference between two sets of forecast errors.
 H_1^1 : the first set of forecasting errors is significantly smaller than the second.
2. H_0^2 : there is no statistical difference between two sets of forecast errors.
 H_1^2 : the second set of forecasting errors is significantly smaller than the first.

It is clear that the sum of the P values of two statistics (S_1 and S_2) is equal to unity. If we define the significance of modified Diebold-Mariano statistics as at least 10% significance level of t distribution, adjusted statistics provide three possible answers to superiority between two rival models:

1. If S_1 is significant, then the former forecasting model outperforms the later model.
2. If S_2 is significant, then the later forecasting model outperforms the former model.
3. If none of S_1 and S_2 is significant, then two models produce equally accurate forecasts.

Tables 11 to 20 present the results of ten groups of modified Diebold-Mariano tests. Tables 11 to 14 provide a comparison between the Kalman filter approach and the four GARCH models. Kalman filter approach is found to significantly outperform bivariate GARCH, BEKK GRACH and GJR GARCH models based on both the MSE and MAE (Tables 11 to 13). No company accepts the hypothesis that these GARCH models significantly outperforms Kalman filter method. In about half of cases, the two forecasting models are found to produce equally accurate forecasts.

Since neither GARCH-X nor Kalman filter can be applied to all firms, the modified Diebold-Mariano tests are valid in a smaller group of forecast errors. Test results presented in Table 14 show that Kalman filter overwhelmingly dominates GARCH-X in one-year forecast samples. In particular, the modified statistics based on MSE in 2001 find evidence in all firms that Kalman filter outperform GARCH-X.

For the two-year forecast horizon, although more forecast errors are found to have no significant difference between each other, Kalman filter still exhibit superiority in some cases. No modified Diebold-Mariano statistics provide evidence for dominance of GARCH-X over Kalman filter.

Modified Diebold-Mariano tests are also applied among GARCH models. Table 14 report the results of tests between bivariate GARCH and BEKK. According to the modified Diebold-Mariano statistics, the standard GARCH model has more accurate forecasts than BEKK in 2003 no matter which error criterion is used. In forecast sample of 2001 and 2002-2003, the test statistics based on MSE supports BEKK and bivariate GARCH respectively; while no preference is found in terms of MAE. Through three forecast samples, equal accuracy is supported by at least 70% of firms; thus the predictive performance of these two GARCH models is fairly similar.

Table 15 reports the results of modified Diebold-Mariano tests between the standard GARCH and GJR specification. The modified test statistics provide conflicting evidence on the dominance of alternative models. In 2001, bivariate GARCH outperforms GJR by having a higher percentage of dominance, in terms of both MSE and MAE. In 2003 and 2002-2003, opposite evidence is found that GJR GARCH is better than bivariate GARCH in few cases. However in all forecast samples, most firms show that forecast errors are not statically different. Thus, bivariate GARCH and GJR have similar forecasting performance in most cases.

Modified Diebold-Mariano tests are applied to a smaller group of forecast errors to detect the superiority between bivariate GARCH and GARCH-X. According to the results reported in Table 16, GARCH-X is found to be superior to bivariate GARCH in one-year forecasts. In two-year forecast sample, evidence is found that bivariate

GARCH outperforms GARCH-X. However, most firms accept the hypothesis that the competing models have similarly accurate forecast errors over different samples.

The results of modified Diebold-Mariano tests between BEKK GARCH and GJR GARCH are reported in table 17. In all forecast horizons, the proportion of firms accepting the superiority of GJR is higher than firms supporting BEKK. Thus, GJR is favored by more firms in terms of forecast accuracy. However, as more than half of the firms provide evidence of equal accuracy between the two GARCH models.

According to the modified Diebold-Mariano test results in Table 18, GARCH-X outperforms BEKK model through different samples in terms of MSE. MAE in 2001 also provides evidence for the dominance of GARCH-X; while in 2003 and 2002-2003 test statistics show that both models have similar level of MAEs. A high proportion of firms support that both forecasting model produce equally accurate forecasts, especially in 2003 and 2002-2003.

Table 19 reports the results from modified Diebold-Mariano tests between GJR GARCH and GARCH-X forecasting models. Modified statistics provide evidence that the forecasting performance of the two models is similar, since most firms accept the hypothesis of equal accuracy. In 2001, GARCH-X shows dominance over GJR in a few cases; while GJR is found to be better in 2003. In forecast period 2002-2003, no significant dominance is found in terms MSE; while GJR is favored by MAE.

Based on the ten groups of modified Diebold-Mariano comparison tests, Kalman filter is the preeminent forecasting model, as it overwhelmingly dominates all GARCH models with significantly smaller forecast errors in most cases. In contrast, none of the firms show that GARCH type models can outperform Kalman filter. Among the GARCH models, forecast performance is generally similar as many firms accept the hypothesis of equal accuracy. In cases of firms that do not accept the

hypothesis of equal accuracy the GJR is the best GARCH specification in terms of return forecasts, followed by bivariate GARCH that also produces accurate out-of-sample forecasts. BEKK shows a little inferior to bivariate GARCH. GARCH-X is found to have similar forecasting performance to GJR; however it can only applied to the firms with cointegrated relationship with the market.

11. Conclusion

This paper empirically estimates the weekly time-varying beta and attempts to forecast the betas of the twenty UK firms. Since the beta (systematic risk) is the only risk that investors should be concern about, prediction of the beta value helps investors to make their investment decisions easier. The value of beta can also be used by market participants to measure the performance of fund managers through Treynor ratio. For corporate financial managers, forecasts of the conditional beta not only benefit them in the capital structure decision but also in investment appraisal. This paper also empirically investigates the forecasting ability of four different GARCH model; standard bivariate GARCH, bivariate BEKK, bivariate GARCH-GJR and the bivariate GARCH-X. The paper also studies the non-GARCH method Kalman filter approach's forecasting ability. The GARCH models apply the conditional variance information to construct the conditional beta series. The Kalman approach recursively estimates the beta series from an initial set of priors, generating a series of conditional alphas and betas in the market model.

The tests are carried out in two steps. In the first step, the actual beta series will be constructed by GARCH models and the Kalman filter approach from 1989 to 2003. In the second step, the forecasting models will be used to forecast time-varying betas and be compared in terms of forecasting accuracy. To avoid the sample effect, three forecast horizons will be considered, including two one-year forecasts 2002 and 2003,

and a two-year horizon from 2002 to 2003. Two sets of forecast are made and the different methods applied compared. In the first test, the time-varying beta is directly forecasted and in the second test the estimated betas are used to forecast stock returns.

The lack of *ex ante* beta values makes it impossible to evaluate the predictive ability of models according to the real future benchmarks. Consequently, *ex post* data must be used as remediation. For instance, sequences of beta will be 'predicted' for the year 2003 based on parameter values derived from 1989 to 2002. Forecasted betas then will be compared to real beta values in 2003. In the third and last step, the empirical results of performance of various models will be produced on the basis of hypothesis tests whether the estimate is significantly different from the real value, which will provide evidences for comparative analysis of merits of different forecasting models. Various measures of forecast errors are calculated on the basis of beta forecasts to assess the relative superiority of alternative models. In order to evaluate the level of forecast errors between conditional beta forecasts and actual values, mean absolute errors (MAE), mean square errors (MSE), mean absolute percentage errors (MAPE) and Theil U statistics are calculated for each forecast. GJR and bivariate GARCH are found to be better compared to other methods in providing beta forecast.

Forecast errors based on return forecasts are employed to evaluate out-of-sample forecasting ability of both GARCH and non-GARCH models. Measures of forecast errors overwhelmingly support the Kalman filter approach. The last comparison technique used is modified Diebold-Mariano test. This test is conducted to detect superiority between two forecasting models at a time. The results again finds evidence in favour of the Kalman filter approach, relative to GARCH models. Both GJR and GARCH-X models appear to have a bit more accurate forecasts than the

bivariate GARCH model. The BEKK model is dominated by all the other competitors. Results presented in this paper advocate further in this field applying different markets, time periods and methods.

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Table 1
Company Profile Table

Name	Products	Industry	Market Capitalisation (m£)
British Airways	Airline services	Transportation	2517.50
TESCO	Mass market distribution	Retailer	18875.26
British American Tobacco	Cigars and Cigarettes	Tobacco	15991.70
BT Group	Telecommunications	Utilities	16269.67
Legal and General	Insurance	Financial	6520.12
Glaxo Smith Kline	Medicines	Pharmaceutical	76153.00
Edinburgh Oil and Gas	Oil and gas	Energy Producer	48.07
Boots Group	Health and beauty products	Retailer	5416.64
Barclays	Banking	Financial	32698.64
Scottish and Newcastle	Beer	Beverage	3380.12
Signet Group	Jewellery and watches	Retailer	1770.29
Goodwin	Mental products	Metal Producer	17.64
British Vita	Polymers, foams and fibers	Chemical	466.62
Caldwell Investments	Ninaclip products	Wholesaler	3.08
Alvis	Military vehicles	Automotive	189.68
Tottenham Hotspur	Football club	Recreation	28.57
Care UK	Health and social care	Service organization	146.84
Daily Mail and Gen Trust	Media products	Printing and Publishing	237.84
Cable and Wireless	Telecommunications	Utilities	3185.61
BAE Systems	Military equipments	Aerospace	5148.61

Table 2
Mean Absolute Error of Return Forecasts (2001)

	GARCH	BEKK	GJR	GARCH-X	Kalman
British Airways	0.0609990	0.0799615	0.0603233		FTC
TESCO	0.0294197	0.0270018	0.0271733		0.0257812
British American Tobacco	0.0322958	0.0332396	0.0347135		0.0298413
BT Group	0.0597085	0.0693117	0.0561728		0.0556705
Legal and General	0.0219667	0.0349400	0.0219525	0.0219152	0.0211787
Glaxo Smith Kline	0.0265273	0.0265332	0.0267266	0.0262428	0.0250460
Edinburgh Oil and Gas	0.0730053	0.0843483	0.0705935		0.0695225
Boots Group	0.0209987	0.0225276	0.0208609		0.0196821
Barclays Bank	0.0277797	0.0325654	0.0284911		0.0277974
Scottish and Newcastle	0.0279828	0.0278869	0.0281130		0.0263320
Singet Group	0.0637875	0.0850078	0.0705701		FTC
Goodwin	0.0279662	0.0255463	0.0274539		0.0258745
British Vita	0.0350545	0.0486594	0.0359354	0.0339518	0.0325118
Caldwell Invs	0.0493035	0.0862989	0.0498145		FTC
Alvis	0.0314207	0.0279000	0.0301953	0.0295452	FTC
Tottenham Hotspur	0.0214986	0.0225482	0.0223097		FTC
Care UK	0.0236118	0.0251053	0.0234808	0.0235961	0.0220384
Daily Mail and Gen	0.0174536	0.0177491	0.0179107		0.0141337
Cable and Wireless	0.0420713	0.0521787	0.0462570		0.0451568
BAE Systems	0.0461277	0.0473308	0.0463786		FTC

Note: FTC stands for 'failed to converge'.

Table 3
Mean Square Error of Return Forecasts (2001)

	GARCH	BEKK	GJR	GARCH-X	Kalman
British Airways	0.0085187	0.0154079	0.0087032		FTC 0.0009391
TESCO	0.0012330	0.0010271	0.0010685		33
British American Tobacco	0.0014981	0.0016344	0.0017977		0.0012786 36
BT Group	0.0053241	0.0087424	0.0045427		0.0042482 37
Legal and General	0.0008527	0.0026156	0.0008538	0.0008509	0.0007586 28
Glaxo Smith Kline	0.0011373	0.0011467	0.0011088	0.0010788	0.0009450 36
Edinburgh Oil and Gas	0.0093925	0.0135059	0.0091701		0.0091493 68
Boots Group	0.0006781	0.0008722	0.0006762		0.0006383 86
Barclays Bank	0.0012553	0.0017128	0.0013166		0.0011286 39
Scottish and Newcastle	0.0012926	0.0013044	0.0012886		0.0012077 83
Singet Group	0.0072991	0.0151196	0.0090872		FTC 0.0019872
Goodwin	0.0026033	0.0015169	0.0020858		18
British Vita	0.0025077	0.0044825	0.0028430	0.0024042	0.0021857 82
Caldwell Invs	0.0071468	0.0190159	0.0071496		FTC
Alvis	0.0020730	0.0017017	0.0019852	0.0018858	FTC
Tottenham Hotspur	0.0007407	0.0008463	0.0007571		FTC 0.0008987
Care UK	0.0009450	0.0010012	0.0009306	0.0009409	88
Daily Mail and Gen	0.0005710	0.0005151	0.0005836		0.0004520 76
Cable and Wireless	0.0044692	0.0076678	0.0044877		0.0038091 86
BAE Systems	0.0042652	0.0044646	0.0042499		FTC

Note: FTC stands for 'failed to converge'.

Table 4

Mean Errors of Return Forecasts (2001)

	GARCH	BEKK	GJR	GARCH-X	Kalman
British Airways	-0.0139102	-0.0162964	-0.0118706		FTC
TESCO	0.0050226	0.0017806	0.0039588		0.0028708
British American Tobacco	0.0083852	0.0077729	0.0095356		0.0084557
BT Group	-0.0012838	0.0110220	-0.0012781		-0.0006238
Legal and General	0.0001848	-0.0007834	0.0003833	0.0003137	0.0008287
Glaxo Smith Kline	0.0013172	0.0026602	0.0011444	0.0017139	0.0013509
Edinburgh Oil and Gas	0.0367699	0.0361849	0.0387579		0.0393829
Boots Group	0.0053399	0.0048794	0.0055962		0.0057619
Barclays Bank	0.0009250	0.0030465	0.0019472		0.0019511
Scottish and Newcastle	0.0089151	0.0075225	0.0090482		0.0075539
Singet Group	0.0168908	0.0088097	0.0229155		FTC
Goodwin	0.0130125	0.0083757	0.0114101		0.0102884
British Vita	0.0039950	0.0038823	0.0018632	0.0040780	0.0042790
Caldwell Invs	0.0146273	-0.0048967	0.0148512		FTC
Alvis	0.0104102	0.0081696	0.0107279	0.0097419	FTC
Tottenham Hotspur	0.0026985	0.0017467	0.0031731		FTC
Care UK	0.0000759	-0.0020731	0.0004696	0.0001375	-0.0003594
Daily Mail and Gen	0.0076791	0.0057418	0.0075297		0.0066064
Cable and Wireless	-0.0201820	-0.0198705	-0.0183247		-0.0183278
BAE Systems	0.0022033	-0.0012331	0.0021877		FTC

Note: FTC stands for 'failed to converge'.

Table 5
Mean Absolute Error of Return Forecasts (2003)

	GARCH	BEKK	GJR	GARCH-X	Kalman
British Airways	0.0416672	0.0477844	0.0432998		0.0409881
TESCO	0.0216474	0.0216491	0.0217277		0.0216511
British American Tobacco	0.0202814	0.0265001	0.0200560		0.0201715
BT Group	0.0201780	0.0256547	0.0206380		0.0187930
Legal and General	0.0297147	0.0405306	0.0297655	0.0296091	0.0290675
Glaxo Smith Kline	0.0224875	0.0224343	0.0227118	0.0224961	0.0221981
Edinburgh Oil and Gas	0.0338654	0.0347903	0.0337039		FTC
Boots Group	0.0173100	0.0170699	0.0175237		0.0174217
Barclays Bank	0.0198811	0.0265896	0.0196401		0.0190972
Scottish and Newcastle	0.0259553	0.0244490	0.0263909		0.0267344
Singet Group	0.0294916	0.0444378	0.0291656		FTC
Goodwin	0.0384271	0.0386126	0.0373638		0.0374500
British Vita	0.0270473	0.0270753	0.0270956	0.0269969	0.0267074
Caldwell Invs	0.0381234	0.0388304	0.0375019		FTC
Alvis	0.0331638	0.0347532	0.0326492	0.0334075	FTC
Tottenham Hotspur	0.0312275	0.0371545	0.0312879		FTC
Care UK	0.0326049	0.0328549	0.0326522	0.0327572	0.0321361
Daily Mail and Gen	0.0122952	0.0134707	0.0117770		0.0099523
Cable and Wireless	0.0544720	0.0648414	0.0537206		0.0514613
BAE Systems	0.0384981	0.0381986	0.0381810		0.0339778

Note: FTC stands for 'failed to converge'.

Table 6
Mean Square Error of Return Forecasts (2003)

	GARCH	BEKK	GJR	GARCH-X	Kalman
British Airways	0.0031605	0.0041235	0.0032571		0.0030147 56
TESCO	0.0007984	0.0007964	0.0008072		0.0008022 28
British American Tobacco	0.0008738	0.0014522	0.0008433		0.0008190 26
BT Group	0.0006732	0.0010549	0.0007048		0.0005873 01
Legal and General	0.0015511	0.0035506	0.0015631	0.0015378	0.0013878 16
Glaxo Smith Kline	0.0007721	0.0007762	0.0007833	0.0007695	0.0007559 15
Edinburgh Oil and Gas	0.0023039	0.0023052	0.0022693		0.0004771 39
Boots Group	0.0004891	0.0004849	0.0005021		0.0006139 51
Barclays Bank	0.0006615	0.0013284	0.0006496		FTC 0.0014880
Scottish and Newcastle	0.0014493	0.0013794	0.0014643		15
Singet Group	0.0014419	0.0034116	0.0014117		FTC 0.0026948
Goodwin	0.0028299	0.0026457	0.0025885		35 0.0012649
British Vita	0.0012937	0.0012966	0.0012873	0.0012671	62
Caldwell Invs	0.0036322	0.0036766	0.0035098		FTC
Alvis	0.0019309	0.0023071	0.0019729	0.0020239	FTC
Tottenham Hotspur	0.0019907	0.0029566	0.0019793		FTC 0.0018157
Care UK	0.0018906	0.0018930	0.0018895	0.0019012	66 0.0002406
Daily Mail and Gen	0.0003092	0.0003634	0.0002870		22 0.0057650
Cable and Wireless	0.0064958	0.0097701	0.0063649		38 0.0019335
BAE Systems	0.0023583	0.0023259	0.0022473		31

Note: FTC stands for 'failed to converge'.

Table 7

Mean Errors of Return Forecasts (2003)

	GARCH	BEKK	GJR	GARCH-X	Kalman
British Airways	0.0045346	0.0042155	0.0057002		0.0046817
TESCO	0.0025815	0.0028179	0.0025901		0.0031636
British American Tobacco	0.0019974	0.0073484	0.0023742		0.0031320
BT Group	-0.0045563	-0.0070892	-0.0040437	-0.0044582	-0.0047429
Legal and General	-0.0045087	-0.0053089	-0.0045062	-0.0010877	-0.0044496
Glaxo Smith Kline	-0.0011045	-0.0005343	-0.0010485		-0.0012215
Edinburgh Oil and Gas	-0.0006010	0.0028190	-0.0000390		FTC
Boots Group	0.0005631	0.0009417	0.0007244		0.0010774
Barclays Bank	0.0005839	0.0024705	0.0007793		0.0004127
Scottish and Newcastle	-0.0079979	-0.0068776	-0.0077126		-0.0067156
Singet Group	0.0036026	-0.0041888	0.0042960		FTC
Goodwin	0.0207486	0.0174581	0.0184627		0.0192450
British Vita	-0.0014307	0.0014910	-0.0015915	-0.0008248	-0.0018519
Caldwell Invs	0.0047800	0.0040074	0.0047867		FTC
Alvis	0.0013305	-0.0009326	0.0000169	0.0002473	FTC
Tottenham Hotspur	0.0009067	-0.0032163	0.0011231		FTC
Care UK	0.0173390	0.0160539	0.0173403	0.0174967	0.0169852
Daily Mail and Gen	-0.0024915	-0.0031226	-0.0025081		-0.0020287
Cable and Wireless	0.0182024	0.0025279	0.0176326		0.0168486
BAE Systems	0.0024500	0.0022334	0.0029007		0.0042813

Note: FTC stands for 'failed to converge'.

Table 8

Mean Absolute Error of Return Forecasts (2002-2003)

	GARCH	BEKK	GJR	GARCH-X	Kalman
British Airways	0.0459901	0.0849055	0.0457304		0.0440916
TESCO	0.0224134	0.0264573	0.0224682		0.0223333
British American Tobacco	0.0281326	0.0312190	0.0268369		0.0264613
BT Group	0.0285032	0.0326030	0.0288145		0.0269189
Legal and General	0.0271959	0.0485533	0.0272949	0.0271602	0.0277687
Glaxo Smith Kline	0.0248275	0.0471357	0.0248880	0.0249294	0.0246228
Edinburgh Oil and Gas	0.0432631	0.0516222	0.0427810		0.0425370
Boots Group	0.0201640	0.0281675	0.0201372		0.0202668
Barclays Bank	0.0220496	0.0288025	0.0220734		0.0214115
Scottish and Newcastle	0.0256477	0.0254817	0.0259981		0.0256141
Singet Group	0.0325030	0.0387632	0.0328427		FTC
Goodwin	0.0329631	0.0422588	0.0333548		0.0335379
British Vita	0.0290202	0.0290309	0.0287858	0.0287817	0.0290522
Caldwell Invs	0.0428244	0.0416144	0.0423947		FTC
Alvis	0.0312607	0.0311505	0.0307495	0.0311206	FTC
Tottenham Hotspur	0.0269991	0.0333856	0.0266551		FTC
Care UK	0.0356891	0.0425404	0.0352456	0.0357548	0.0348651
Daily Mail and Gen	0.0129266	0.0120385	0.0124671		0.0109882
Cable and Wireless	0.0619775	0.0654206	0.0615435		0.0594908
BAE Systems	0.0451115	0.0513588	0.0449973		0.0413631

Note: FTC stands for 'failed to converge'.

Table 9
Mean Square Error of Return Forecasts (2002-2003)

	GARCH	BEKK	GJR	GARCH-X	Kalman
British Airways	0.0035477	0.0158525	0.0035241		0.0032736 81
TESCO	0.0008249	0.0012067	0.0008287		0.0008067 62
British American Tobacco	0.0015181	0.0020716	0.0013841		0.0013312 50
BT Group	0.0015129	0.0018350	0.0015477		0.0013978 48
Legal and General	0.0013661	0.0051013	0.0013773	0.0013611	0.0013659 09
Glaxo Smith Kline	0.0009887	0.0052613	0.0009951	0.0009903	0.0009746 88
Edinburgh Oil and Gas	0.0034091	0.0049787	0.0033457		0.0032596 12
Boots Group	0.0006917	0.0015269	0.0006941		0.0006789 60
Barclays Bank	0.0008628	0.0016418	0.0008659		0.0008159 46
Scottish and Newcastle	0.0012144	0.0012788	0.0012195		0.0011925 70
Singet Group	0.0018915	0.0024506	0.0019006		FTC 0.0027414
Goodwin	0.0026893	0.0050886	0.0026996		18 0.0013717
British Vita	0.0013739	0.0013772	0.0013520	0.0013505	09
Caldwell Invs	0.0047566	0.0048939	0.0046990		FTC
Alvis	0.0016677	0.0016299	0.0016675	0.0016968	FTC
Tottenham Hotspur	0.0018065	0.0030074	0.0017974		FTC 0.0021645
Care UK	0.0022527	0.0040282	0.0022218	0.0022626	37 0.0002543
Daily Mail and Gen	0.0003044	0.0005721	0.0002884		07 0.0110453
Cable and Wireless	0.0119222	0.0121186	0.0117780		37 0.0038713
BAE Systems	0.0046611	0.0055511	0.0046584		04

Note: FTC stands for 'failed to converge'.

Table 10

Mean Errors of Return Forecasts (2002-2003)

	GARCH	BEKK	GJR	GARCH-X	Kalman
British Airways	0.0050497	0.0026395	0.0039452		0.0043033
TESCO	0.0009001	0.0007283	0.0008637		0.0006214
British American Tobacco	0.0040858	0.0030272	0.0032110		0.0032309
BT Group	-0.0020439	-0.0021176	-0.0017494		-0.0026337
Legal and General	-0.0028606	-0.0029936	-0.0029148	-0.0027922	-0.0032973
Glaxo Smith Kline	-0.0014384	-0.0015465	-0.0014209	-0.0012542	-0.0020864
Edinburgh Oil and Gas	0.0005294	0.0004529	0.0003326		0.0005576
Boots Group	0.0021256	0.0020848	0.0022265		0.0018955
Barclays Bank	0.0004500	0.0003193	0.0003877		0.0002965
Scottish and Newcastle	-0.0036630	-0.0036964	-0.0035048		-0.0034875
Singet Group	0.0016539	0.0015233	0.0016214		FTC
Goodwin	0.0109205	0.0115466	0.0113240		0.0111923
British Vita	0.0034881	0.0033962	0.0033760	0.0034559	0.0033513
Caldwell Invs	0.0052453	0.0048303	0.0052509		FTC
Alvis	0.0051217	0.0048099	0.0043986	0.0042584	FTC
Tottenham Hotspur	-0.0039079	-0.0037993	-0.0037958		FTC
Care UK	0.0059078	0.0059754	0.0058244	0.0059090	0.0054745
Daily Mail and Gen	-0.0040918	-0.0041134	-0.0041065		-0.0043576
Cable and Wireless	-0.0063888	-0.0061460	-0.0063914		-0.0058531
BAE Systems	-0.0040685	-0.0047480	-0.0046585		-0.0023001

Note: FTC stands for 'failed to converge'.

Table 11

Percentage of Dominance of Kalman Filter over Bivariate GARCH						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	57.14	57.14	53.33	33.33	56.25	50.00
Worse	0	0	0	0	0	0
Equal Accuracy	42.86	42.86	46.67	66.67	43.75	50.00

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant difference between forecast errors. The significance is defined as at least 10% significance level of t distribution.

Table 12

Percentage of Dominance of Kalman Filter over BEKK GARCH						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	57.14	50	53.33	40.00	56.25	43.75
Worse	0	0	0	0	0	0
Equal Accuracy	42.86	50	46.67	60.00	43.75	56.25

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant different between forecast errors. The significance is defined as at least 10% significance level of t distribution.

Table 13

Percentage of Dominance of Kalman Filter over GJR GARCH						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	50.00	57.14	66.67	46.67	62.50	37.50
Worse	0	0	0	0	0	0
Equal Accuracy	50.00	42.86	33.33	53.33	37.50	62.50

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant different between forecast errors. The significance is defined as at least 10% significance level of t distribution.

Table 14

Percentage of Dominance of Kalman Filter over GARCH-X						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	100.00	50.00	75.00	25.00	25.00	25.00
Worse	0	0	0	0	0	0
Equal Accuracy	0	50.00	25.00	75.00	75.00	75.00

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant different between forecast errors. The significance is defined as at least 10% significance level of t distribution.

Table 15

Percentage of Dominance of Bivariate GARCH over BEKK GARCH						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	0	5.00	15.00	25.00	15.00	5.00
Worse	5.00	5.00	0	5.00	10.00	5.00
Equal Accuracy	95.00	90.00	85.00	70.00	75.00	90.00

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant different between forecast errors. The significance is defined as at least 10% significance level of t distribution.

Table 16

Percentage of Dominance of Bivariate GARCH over GJR GARCH						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	10.00	25.00	5.00	5.00	5.00	5.00
Worse	5.00	15.00	10.00	5.00	15.00	15.00
Equal Accuracy	85.00	60.00	80.00	90.00	80.00	80.00

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant different between forecast errors. The significance is defined as at least 10% significance level of t distribution.

Table 17

Percentage of Dominance of Bivariate GARCH over GARCH-X						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	0	0	0	0	20.00	20.00
Worse	20.00	40.00	20.00	0	0	0
Equal Accuracy	80.00	60.00	80.00	100.00	80.00	80.00

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant different between forecast errors. The significance is defined as at least 10% significance level of t distribution.

Table 18

Percentage of Dominance of BEKK GARCH over GJR GARCH						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	10.00	15.00	10.00	5.00	5.00	5.00
Worse	15.00	20.00	20.00	20.00	20.00	15.00
Equal Accuracy	75.00	65.00	70.00	75.00	75.00	80.00

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant different between forecast errors. The significance is defined as at least 10% significance level of t distribution.

Table 19

Percentage of Dominance of BEKK GARCH over GARCH-X						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	0	0	0	0	0	0
Worse	20.00	40.00	20.00	0	20.00	0
Equal Accuracy	80.00	60.00	80.00	100.00	80.00	100.00

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant different between forecast errors. The significance is defined as at least 10% significance level of t distribution.

Table 20

Percentage of Dominance of GJR GARCH over GARCH-X						
Hypothesis	2001		2003		2002-2003	
	MSE	MAE	MSE	MAE	MSE	MAE
Better	0	0	20.00	20.00	20.00	20.00
Worse	20.00	20.00	0	0	20.00	0
Equal Accuracy	80.00	80.00	80.00	80.00	60.00	80.00

Note:

This table presents the proportion of firms that accept the three hypotheses. The statistic is the modified Diebold-Mariano test statistic, using MSE and MAE as the error criterion. Better means the former model dominate the later; while worse means the later model significantly outperform the former. Equal accuracy indicates no significant different between forecast errors. The significance is defined as at least 10% significance level of t distribution.

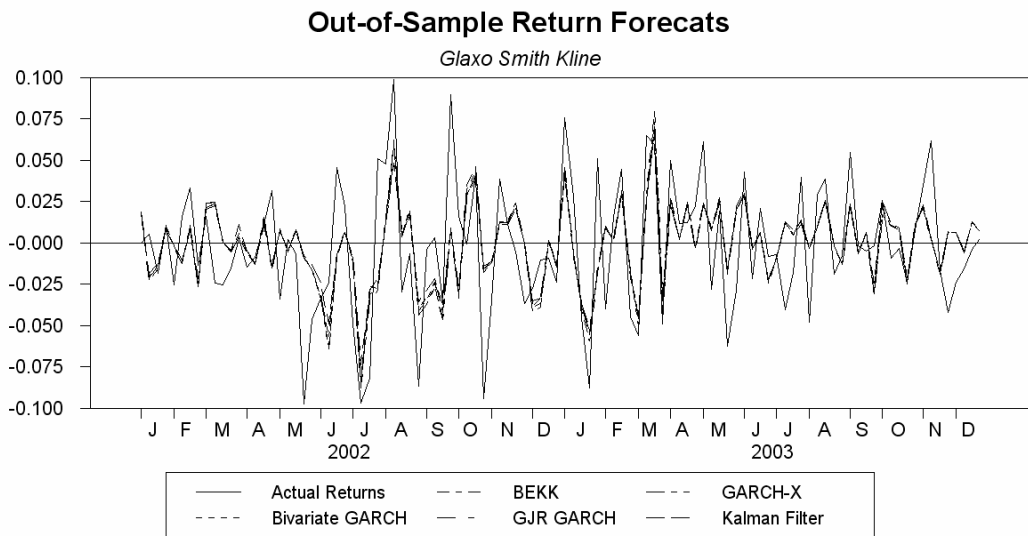
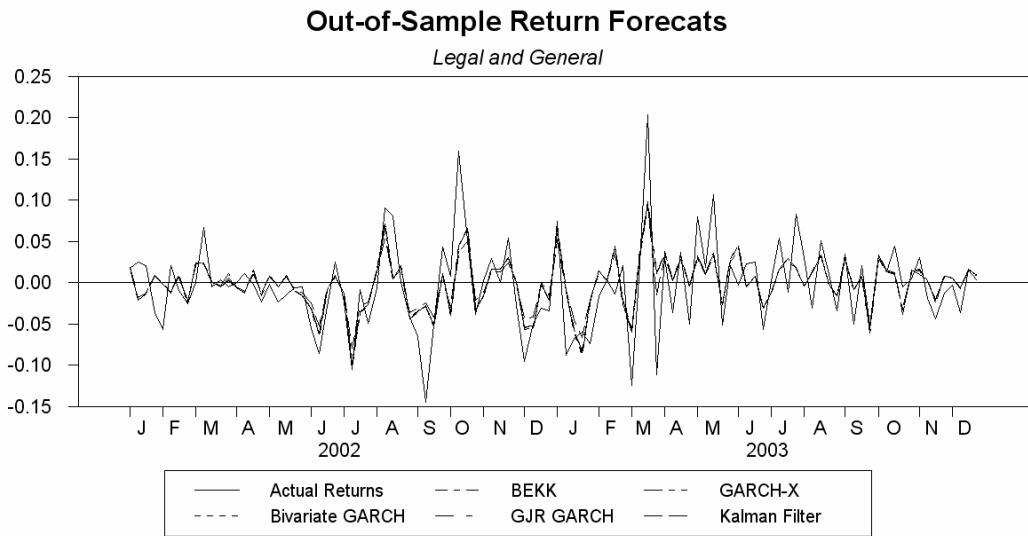


Figure 1